# Humans vs. AI: Robot Soccer and Gran Turismo

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# UT Austin: Exciting Times — Year of AI!

- NSF Institute for Foundations of Machine Learning (IFML)
  Machine Learning Laboratory (MLL)
- Bridging Barriers: Good Systems
  - Inspired by One Hundred Year Study on AI (AI100)
- Director of Texas Robotics
  - Ribbon cutting on new building in 2021



# The Big Scientific Questions of our Time

- How did the universe originate?
- How did life on Earth originate?
- What is the nature of intelligence?

# The Nature of Intelligence

### How Can we Study it?

- Think about it Philosophy
- Study human (or other animal) behavior Psychology
- Study human (or other animal) brains Neuroscience
- Build and analyze intelligent artifacts Computer Science

# A Goal of Al and Robotics

Robust, **fully autonomous** agents in the real world

#### How?

- Build complete agents to perform increasingly complex tasks Complete agents: sense, decide, and act — closed loop
- Drives research on component algorithms, theory
  - Improve from experience
  - Interact with other agents

(Machine learning) (Multiagent systems)

"Good problems produce good science"

### **My Research Problem**

To what degree can autonomous intelligent agents learn in the presence of teammates and/or adversaries in real-time, dynamic domains?

#### **Research Areas**

- Autonomous agents
- Multiagent systems
- Robotics
- Machine learning
  - Reinforcement learning



# RoboCup Soccer

- Grand challenge: beat World Cup champions by 2050
- Still in relatively early stages
- Many virtues as a challenge problem:
  - Incremental challenges, closed loop at each stage
  - Robot design to multi-robot systems
  - Relatively easy entry
  - Inspiring to many
- Visible progress









Middle-sized League











Humanoid League





# RoboCup@Home





# **Reinforcement Learning**

Supervised learning mature [PyTorch]

For agents, reinforcement learning most appropriate



- Foundational theoretical results
- Applications require innovations to scale up

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# **BE a reinforcement learner**

- You, as a group, act as a learning agent
- Actions: Wave, Stand, Clap
- Observations: colors, reward
- Goal: Find an optimal policy
  - Way of selecting actions that gets you the most reward

# How did you do it?

- What is your policy?
- What does the world look like?

# Formalizing What Just Happened

#### Knowns:

- $\mathcal{O} = \{ \text{Blue}, \text{Red}, \text{Green}, \text{Black}, \ldots \}$
- Rewards in IR
- $\mathcal{A} = \{ \textit{Wave}, \textit{Clap}, \textit{Stand} \}$

 $o_0, a_0, r_0, o_1, a_1, r_1, o_2, \dots$ 

#### **Unknowns:**

- $\mathcal{S} = 4x3$  grid
- $\mathcal{R}: \mathcal{S} \times \mathcal{A} \mapsto \mathbb{R}$
- $\mathcal{T} = \mathcal{S} \mapsto \mathcal{O}$
- $\mathcal{P}: \mathcal{S} \times \mathcal{A} \mapsto \mathcal{S}$

$$s_0, o_0, a_0, r_0, s_1, o_1, a_1, r_1, s_2, o_2, \dots$$

 $o_i = \mathcal{T}(s_i)$   $r_i = \mathcal{R}(s_i, a_i)$ 

 $S_{i+1} = \mathcal{P}(S_i, a_i)$ 

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GT Sophy

### Where are we now?

#### Me: Lots of open research challenges

- Professor of Computer Science at UT Austin
- Machine Learning Lab, Good Systems,
- Director of Texas Robotics
- Executive Director of Sony AI America
- You: Lots of choices and opportunities
  - Where will you go to college?
  - What will you study?
  - What will your lifelong challenge be?
  - Opportunities: UTCS, Turing Scholars, FRI, TR
  - AI: Thriving, but with concerns

# A Goal of Al

### Robust, fully autonomous agents in the real world

What happens when we achieve this goal?





- 50 years earlier? Or 50 years later?
- Not clear world changing in many ways for the worse

Al can be a part of the solution

# Reality



### **Perceptions**



# Uncertainty

